# Meeting 10

Date: 19 – June – 2020

Meeting Online ZOOM

Meeting ID: 748050970

Agenda

* Simulating EZ10 in UWA campus

## Attendance

* Oluwafemi Stephen Arowosafe
* Guangming Chen
* Yunzhuo Chen
* Gerardo Cisneros Mendoza
* Yuan Shi
* Thomas Braunl
* Craig Boyle

## Glossary of terms and acronyms

CARLA - Open-source simulator for autonomous driving research.

ROS - Robot Operating System. A flexible framework for writing robot software.  
EZ10 – Easy Mile Autonomous Shuttle

## Minutes

* Measure and change scale of roads.
* Check and ensure build heights are appropriate also some buildings appear too close (resulting in vehicle collusion).
* Adjust flickering walls, change to texture if necessary.
* Create bridge that links top of the stairs to building by REIDS library.
* Place all lidar sensors in correct locations and visualize readings using rviz
* Run a terminal to visualize memory usage whenever simulation is carried out (ensure this is done during next presentation)
* Give a feedback on possible implementation of IMU sensor for carla simulation

## Attachments

No attachments included.